Semi-automation for mapping Cowardin classes and wetland vegetation in Alaska

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Acknowledgements

AKVEG Map Development

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Chenega NWI Mapping

Lindsey Flagstad, Anjanette Steer

Funding ADF&G, BLM, NPS, and EPA

Field Data

Numerous ecologists and technicians for over 30 years!

Outline

- 1. Why change a good thing?
- 2. Automated polygon delineation (image segmentation + aggregation)
- 3. Mapping wetlands directly
- 4. Mapping wetland components
- 5. Conclusion and questions

Why change a good thing?

Manual delineation is a "tried and true" method to produce reliable results given a knowledgeable analyst.



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Automated methods offer:

- 1. Statistically robust accuracy assessment.
- 2. Consistency at large extents.
- 3. Integration of multi-parameter wetland attributes.
- 4. Repeatability for updates and alterations.
- 5. Cost efficiency for large regions.



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Goal: demonstrate ideas to integrate *manual delineation* and *automated methods* while retaining strengths



Definitions and clarifications

Wetlands: defined according to Cowardin classification

1-parameter wetlands: defined based solely on dominance of hydrophytic vegetation

3-parameter wetlands: defined based on a. dominance of hydrophytic vegetation b. substrate is predominantly undrained hydric soil c. saturated/covered with water part of growing season

Wetland plant communities: defined according to U.S. National Vegetation Classification



Definitions and clarifications



AKVEG Map: high ecological and spatial resolution





- Collaborative effort mapping vegetation composition & structure for Alaska
- Currently available: foliar cover of plant species, aggregates, and functional types (version 1.0)
- Nawrocki et al. 2021 & Macander et al. 2022

AKVEG Map represents wetland plant communities (USNVC)



Break ecological complexity to manageable units.

Two types of maps:



Continuous maps show "what is present" using numbers

Two types of maps:

Categorical maps describe what the feature "looks like"

Imagery © Maxar 2021

Existing Vegetation Types (USNVC Alliances)

Semi-automated workflow

Image segments provide "building blocks" for mapping.

Labeling model assigns initial classes to segments.

Like classes aggregated to features.

Image segments developed from high-res imagery

Form polygons based on aggregated model predictions

Aggregate to MMU (0.5 acre)

Semi-automated workflow

Accuracy assessment identifies where analyst effort needed.

Direct mapping starts with manual training polygons

Propagate labels to segments using trained model

Statistically robust accuracy assessment

Study area (yellow) divided into cross validation blocks (white)

Training data in each block retained once as independent test partition of cross validation

Identifies problems related to:

- 1. Misclassification/omission
- 2. Ecological ambiguity
- 3. Analyst errors/inconsistency
- 4. Additional data needs
- 5. Model error (analyst's effort needed)

Identify where analyst's effort is best spent

Semi-automated workflow

Mapping wetland components

- Eriophorum vaginatum (tussock cottongrass) is FACW
- FACW definition: predominately occur in hydric soils, geomorphic settings where water saturates or floods the soil at least seasonally.
- Summary of 187 sites across Alaska of paired vegetation plots and soil pits:
 - 52% of occurrences in mesic soils
 - 48% of occurrences in hydric soils

Net effect: FACW designation drives thousands of acres of 1-parameter mapped wetlands

Soil and geophysical parameters

Map root zone moisture regime and geophysical features

Growing season % surface water

Percent of season when surface water is present

Surface water on June 27, 2018

Not surface water (overtopped) by July 30, 2018

Tidal and flooding patterns represented as %

Tidal and flooding patterns represented as %

Mapping wetland vegetation cover: obligate wetland sedges

0

Percent 50 0

Consistent and cost efficient for large regions

Interpreting predictive R^2 and RMSE

- Predictive *R*² is the *R*² of the model predictions, not of the model
- Calculated from a simple OLS model for observed values as a function of predicted values where the intercept is 0 and the slope coefficient is 1.
- The amount of "generalization".
- RMSE is in the same units as the dependent variable.
- The "discriminatory" power of the model.

Map wetland vegetation types using programmatic key

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Separate similar types using component indicators

Should it be mapped as wetland? It depends...

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1-parameter: **Yes...** but is *Eriophorum vaginatum* reliable in this context?

Should it be mapped as wetland? It depends...

3-parameter: No.

- 1. Absence of hydric soils.
- 2. Not seasonally or partially inundated.

Semi-automated workflow

Workflow is scripted for repeatability.

Analyst revises feature polygons, corrects some labels, and adds non-modeled features.

Analyst drives the classification.

KOUG

Roland

Computational support for the *synthesis* of data.

Roland

HAMMONT

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Conclusion

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Combined with a knowledgeable analyst, workflow can combine benefits of *automated* and *manual* methods.

Presented as an idea rather than a true proof of concept.

Data and code availability

Geospatial data: <u>https://accscatalog.uaa.alaska.edu</u>

Code repository: <u>https://github.com/accs-uaa</u>

The AKVEG Map

Continuous foliar cover of species & aggregates: <u>https://accscatalog.uaa.alaska.edu</u> Time-series of plant functional types: <u>https://daac.ornl.gov</u> (Macander et al. 2022)

AKVEG Database: https://akveg.uaa.alaska.edu

Vegetation Mapping Standards

Alaska Vegetation Technical Working Group: https://agc.dnr.alaska.gov

Results: tealeaf willow (Salix pulchra)

obs.: 60 (out of 66)

