An aerial photograph of a rural landscape with a grid overlay. Large areas of the land are covered with a blue hatched pattern, representing mapped wetlands. The hatched areas follow the paths of waterways and cover various types of terrain, including fields and wooded areas. The text is centered over the map.

**Hype or Panacea: Changing the Wetland
Mapping Ecosystem with Automated
Techniques and High Resolution Data...
But is it NWI Compliant?**

Process Tree

- 04:29.024 Seg4
 - <0.001s at Seg4: fill pixels in Layer 2 using pixels classified as all
 - 04:06.763 60 [shape:0.1 compct.:0.6] creating 'Seg4'
 - 22.136 2x at Seg4: spectral difference 13
 - 0.016 4x with Area < 2000 m² at Seg4: remove objects (merge by shape)
 - [at Seg4: spectral difference 12]
 - 0.078 2x with Arithmetic Feature 1 > 0.935 and Arithmetic Feature 1 < 1.1 at Seg4: r
 - <0.001s 5x with Area < 2500 m² at Seg4: remove objects (merge by shape)
 - 0.016 at Seg4: OpenWater
 - 0.015 2x with Arithmetic Feature 1 > 1.11 and Arithmetic Feature 1 < 2 at Seg4: mer
 - <0.001s with Area < 2200 m² at Seg4: if (condition undefined)
 - OpenWater with Area > 2230 m² at Seg4: merge region
 - at Seg4: unclassified
- Segment_wetlands
 - 110 [shape:0.1 compct.:0.2] creating 'Wetlands'
 - 3x at Wetlands: spectral difference 10
 - 3x with Area < 2500 m² at Wetlands: remove objects (merge by shape)
 - 2x contrast filter segmentation (Layer 2) creating 'Wetlands'
 - 2x with Arithmetic Feature 1 > 0.89 and Arithmetic Feature 1 < 1.2 at Wetlands: merg

Class Hierarchy

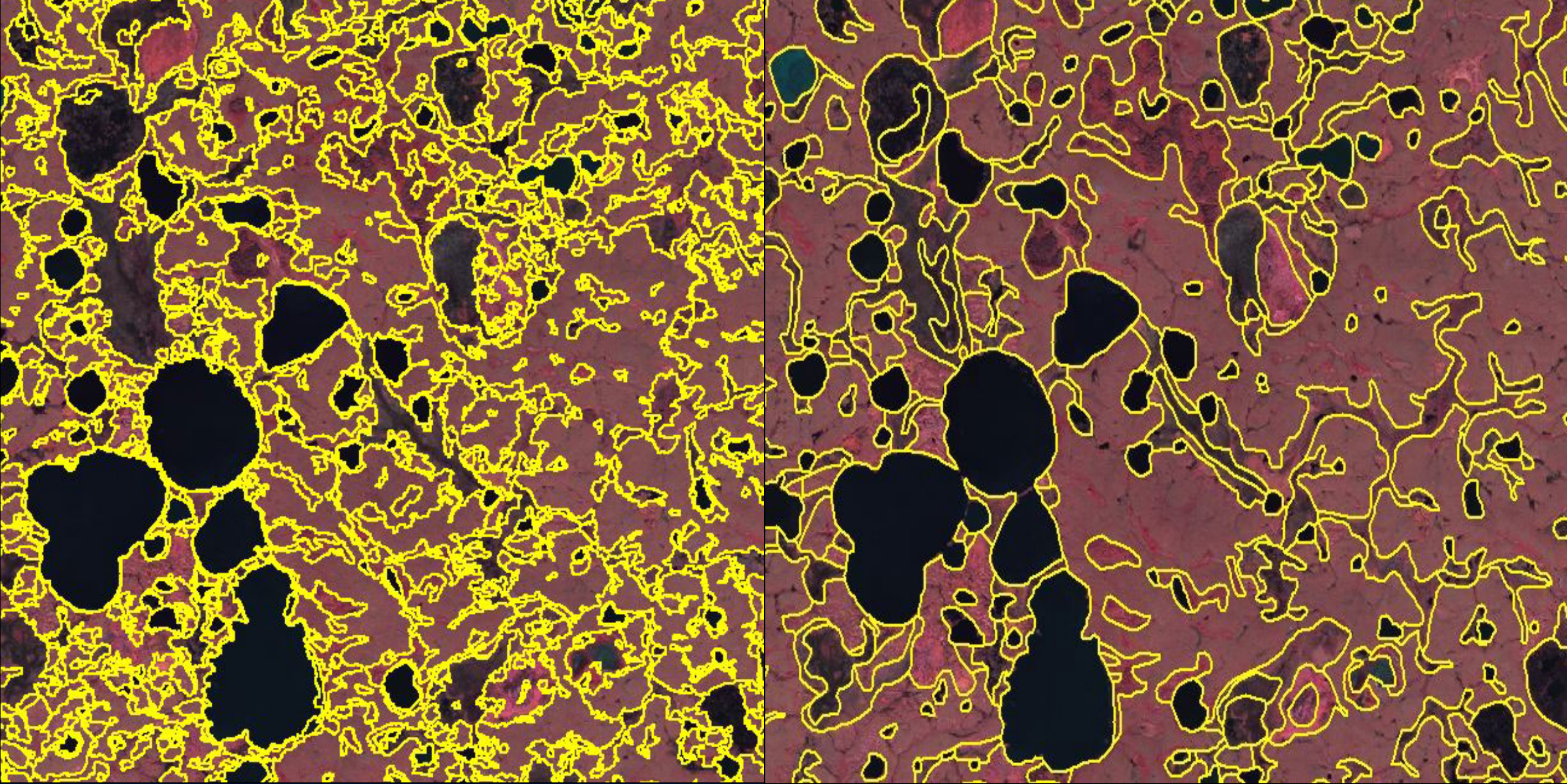
- classes
 - OpenWater
 - Wetlands

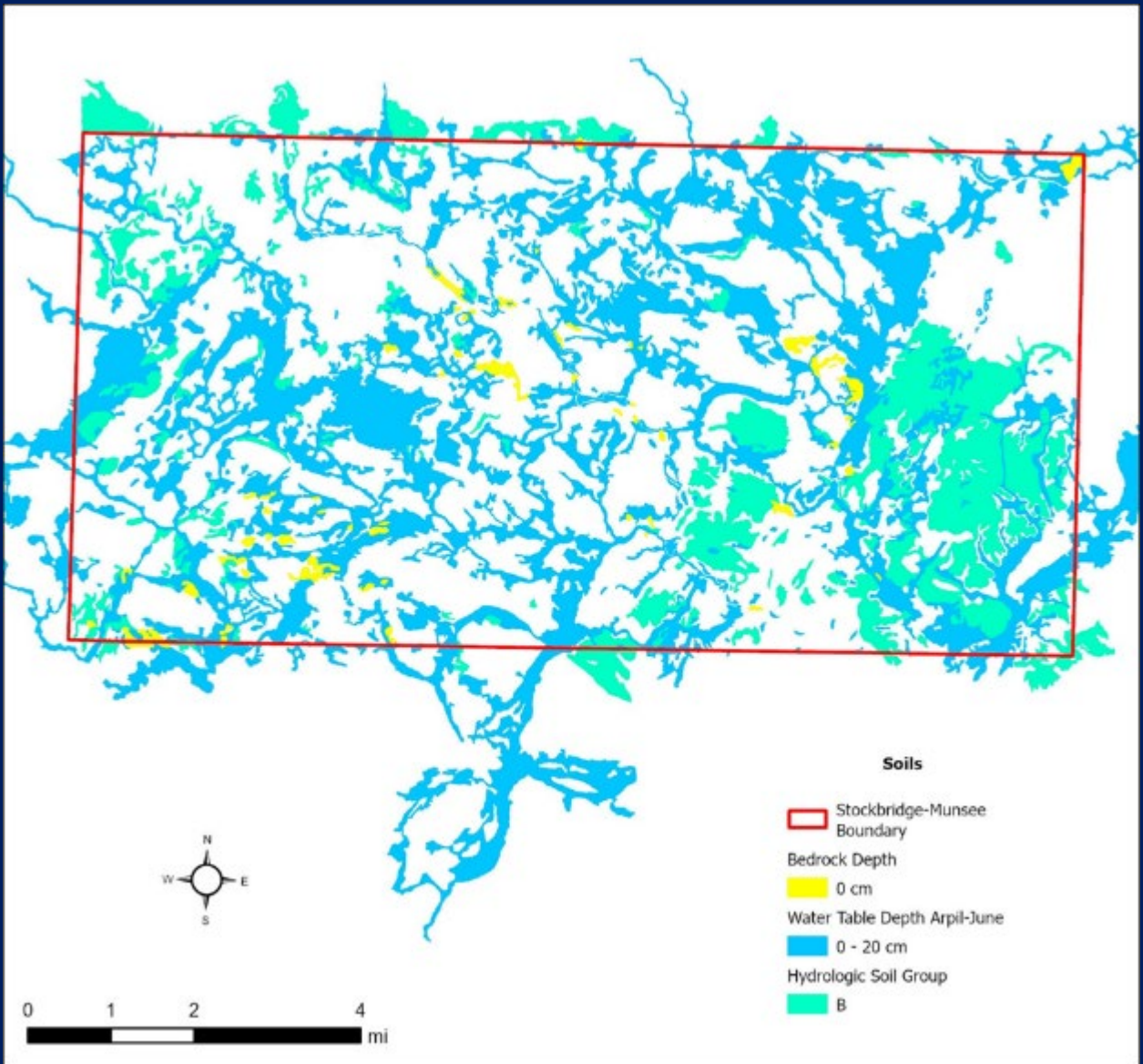
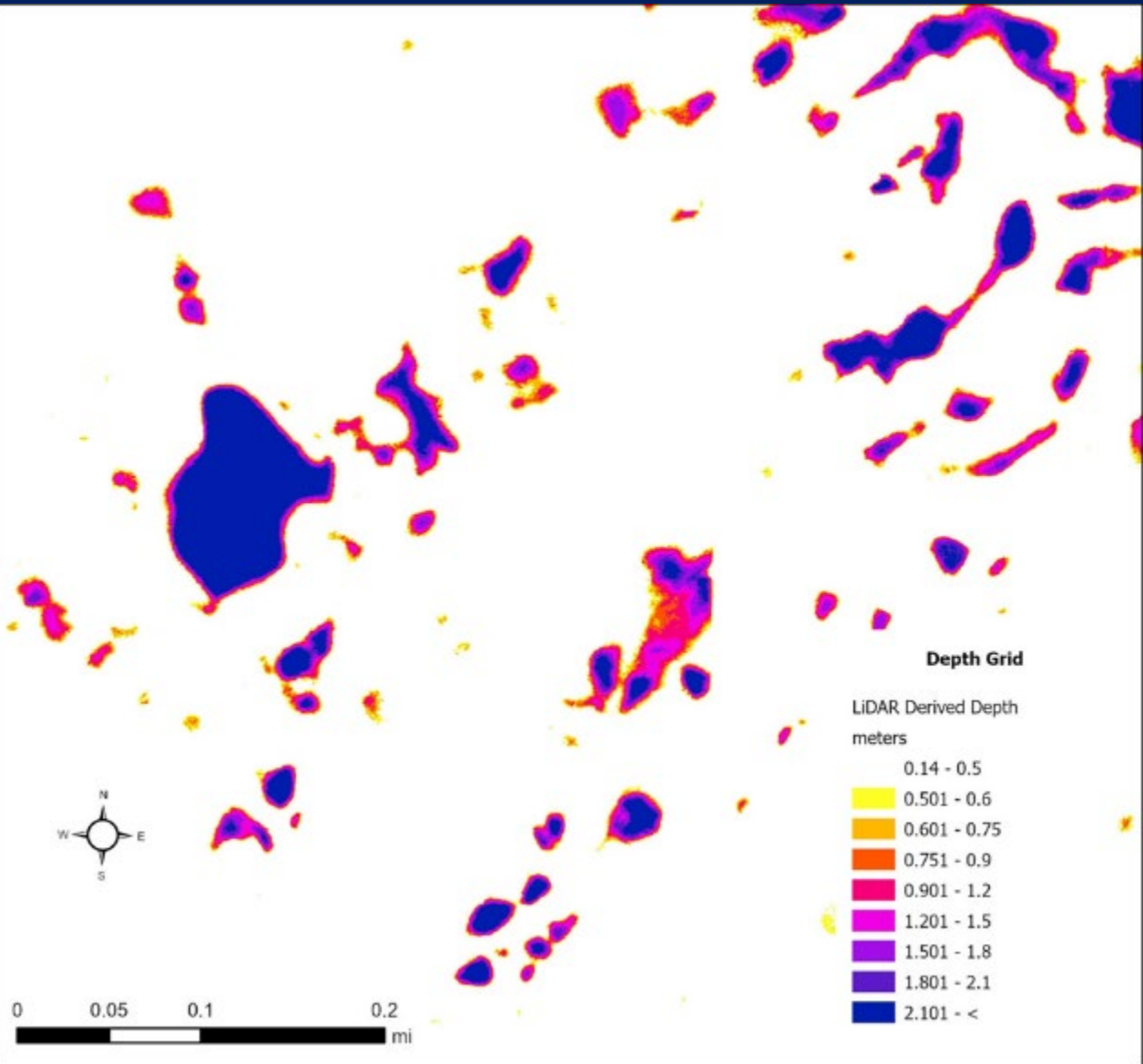
Feature View

- Object features
- Class-Related features
- Linked Object features
- Scene features
- Process-Related features
- Region features
- Image Registration features
- Metadata
- Feature Variables

Image Object Information

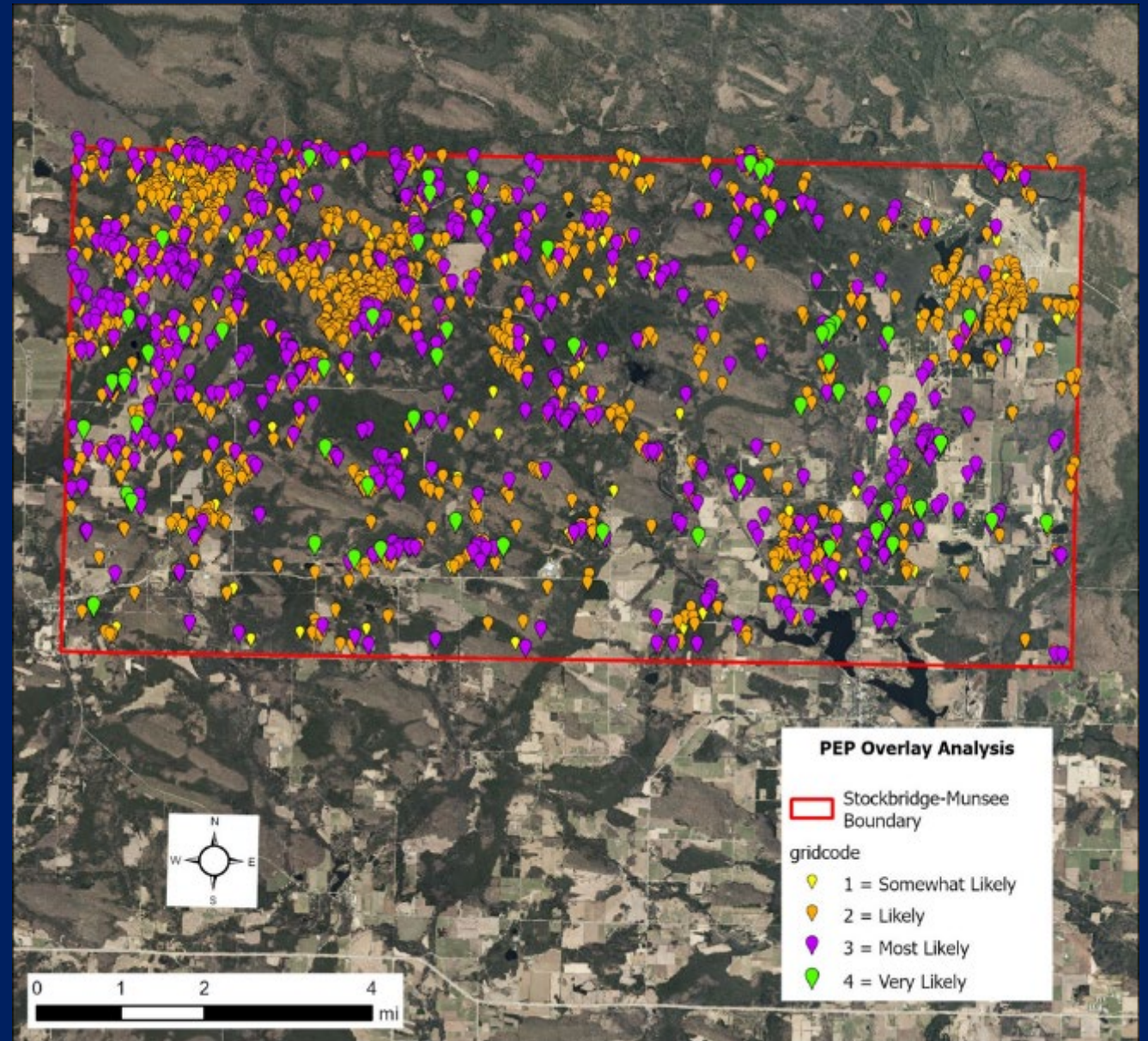
Feature	Value
Selectable features	
No Feature or Image O...	



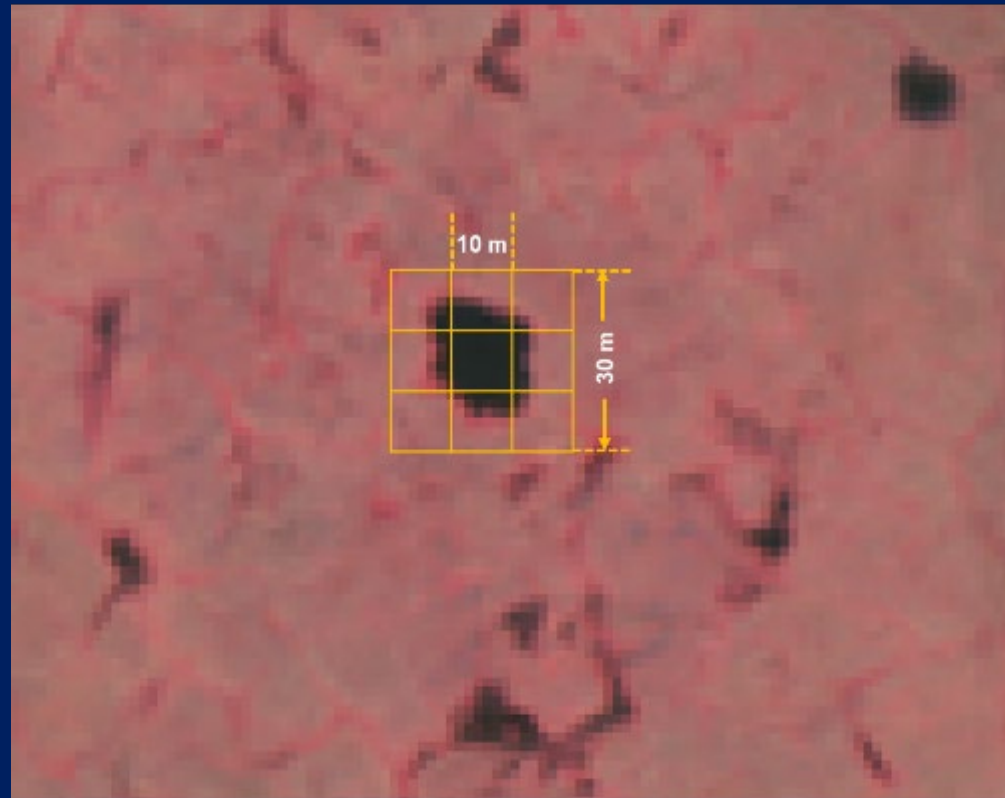


Potential Ephemeral Pond Identification

A Wetland Mapping Update and Identification of Potential Ephemeral Ponds for the Stockbridge-Munsee Community

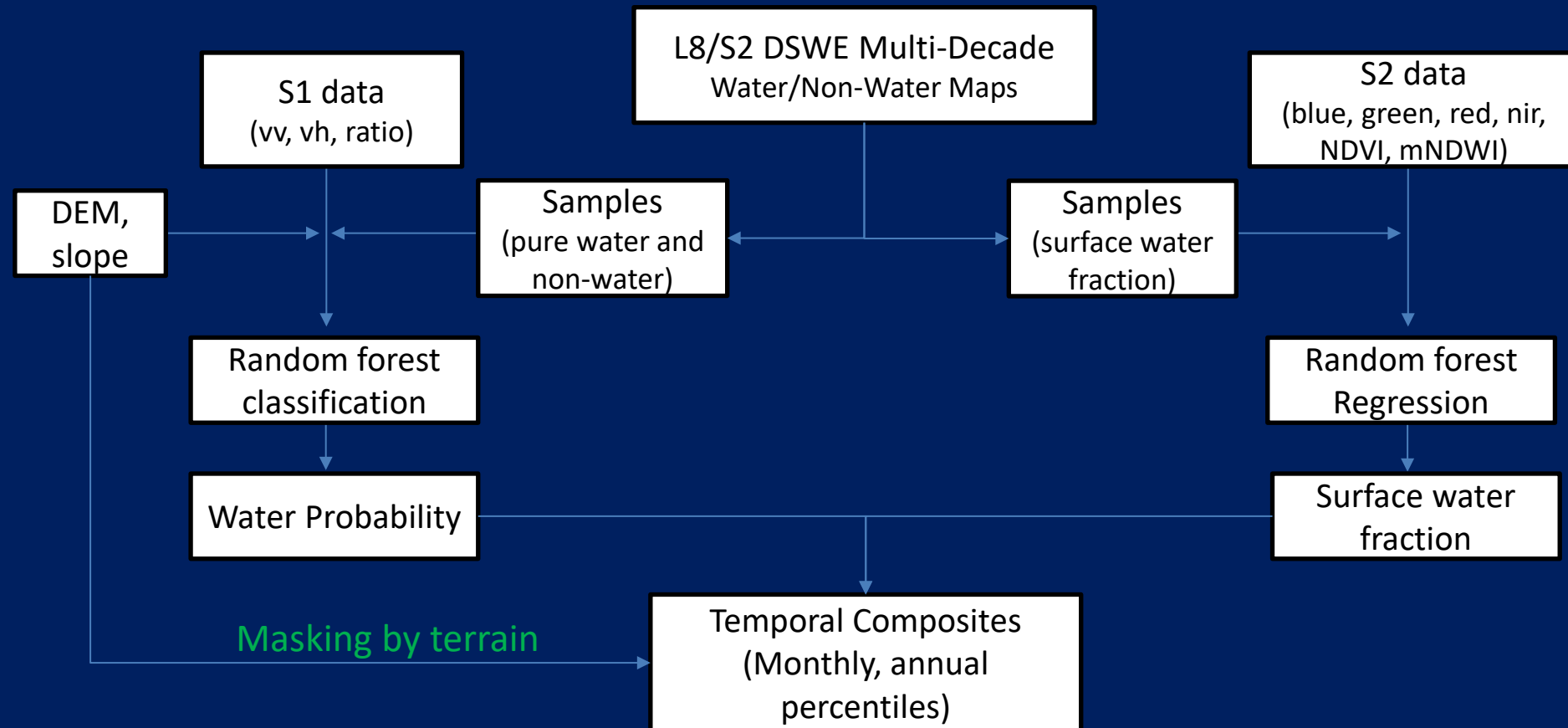


Mapping Algorithms Designed to Capture Small Features using Surface Water Fraction (SWF)



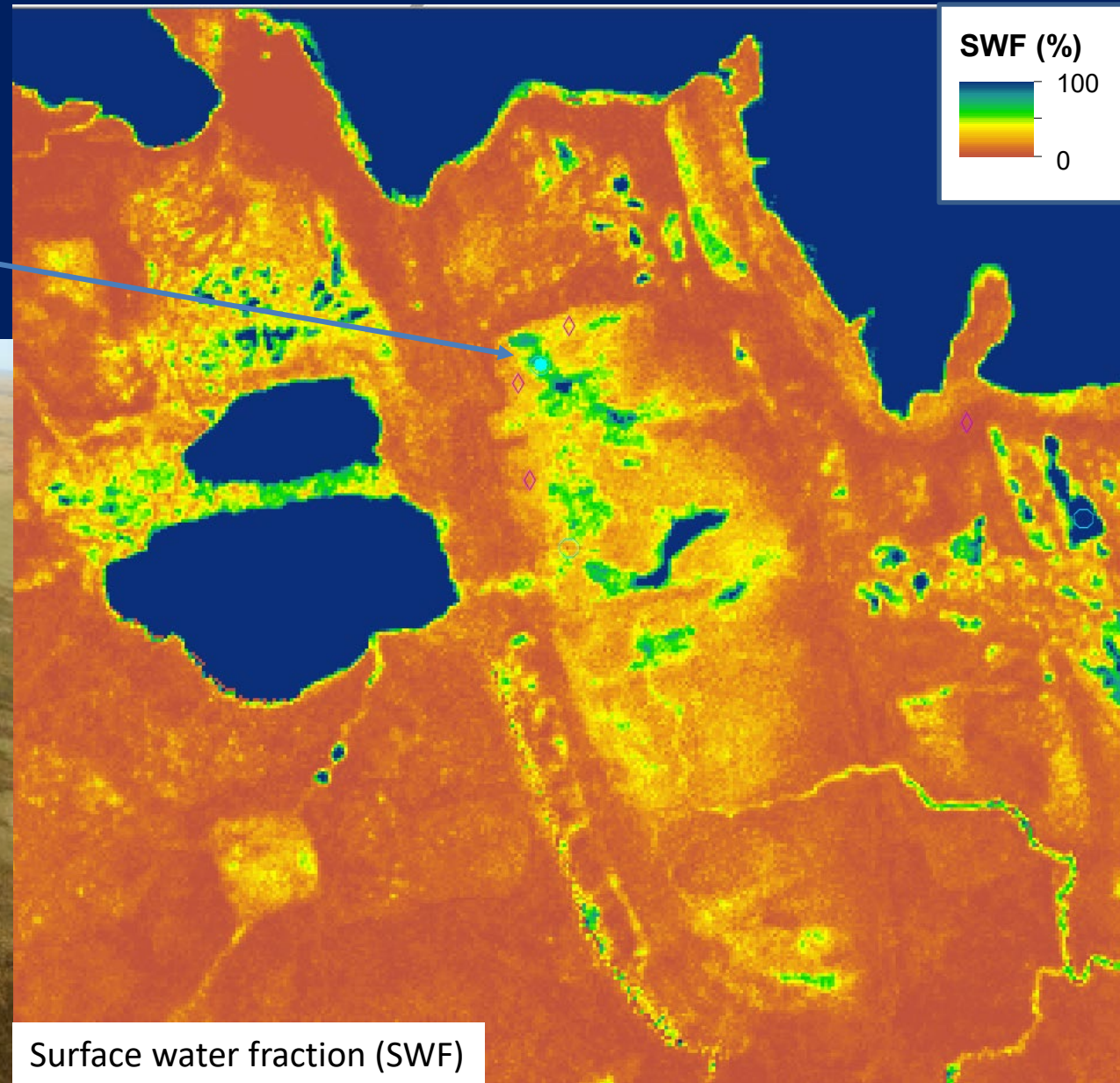
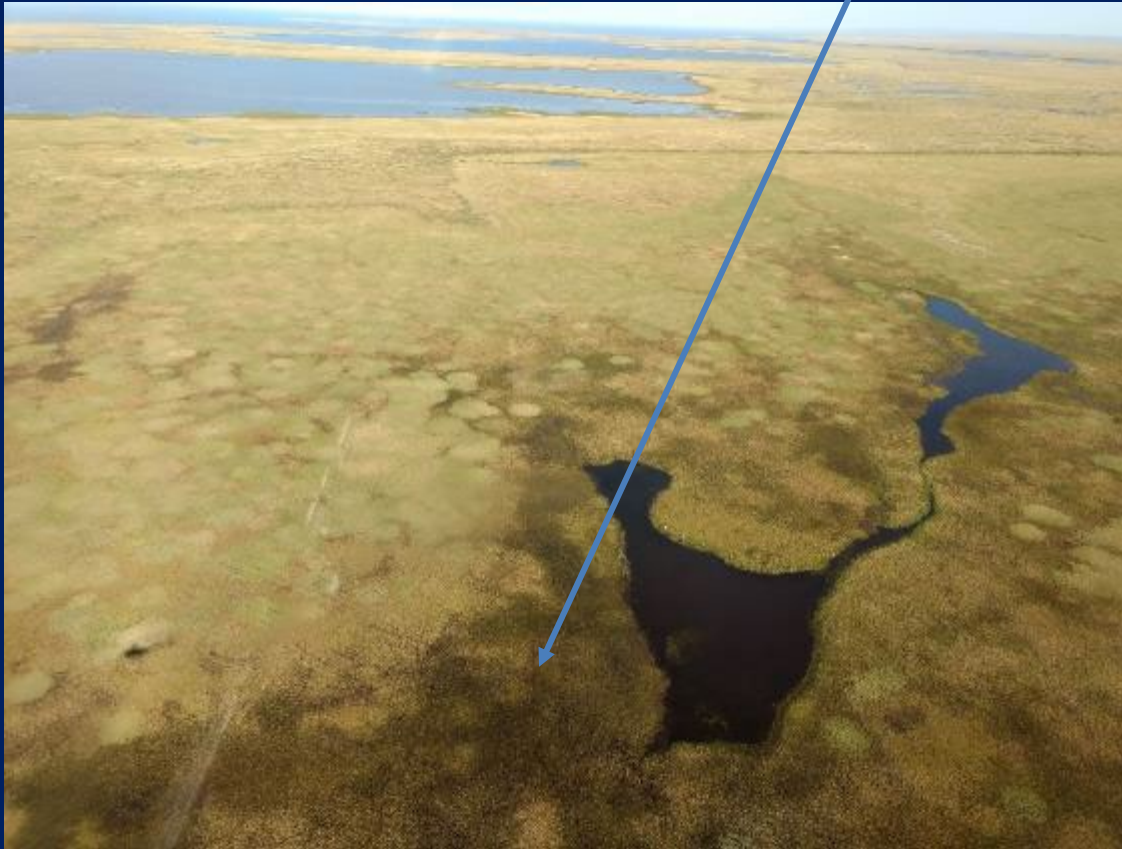
SWF is not indicative of saturation, which needs to be modeled separately

Processing Flow



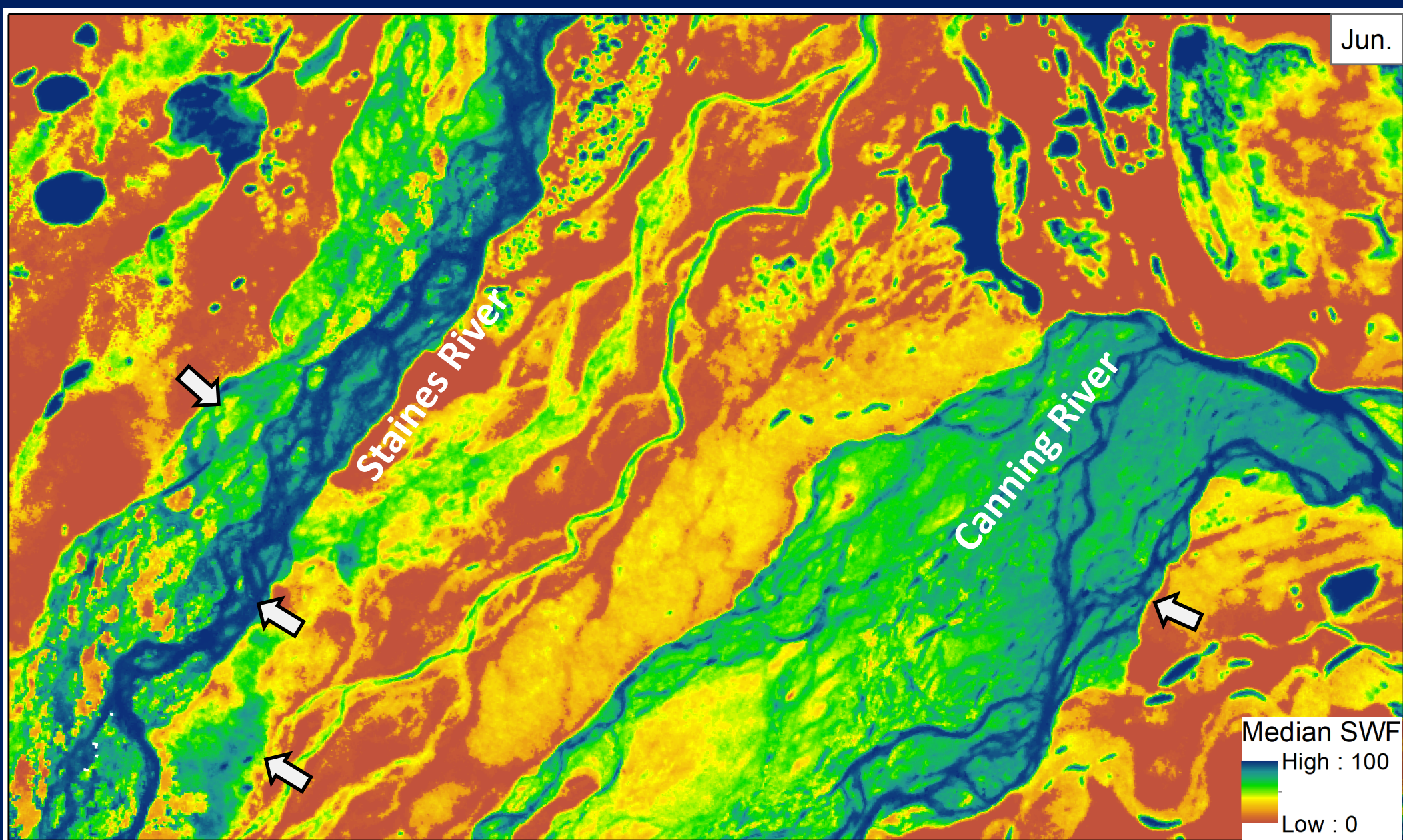
Water Regime Gradients Well Captured

Semi-permanently
flooded area



Surface water fraction (SWF)

Monthly
SWF
Composites



Simplified PW GIS Model

$$PW = (A + B) - (W + U)$$

A = CTI values > 9.5* (*raster cells*)

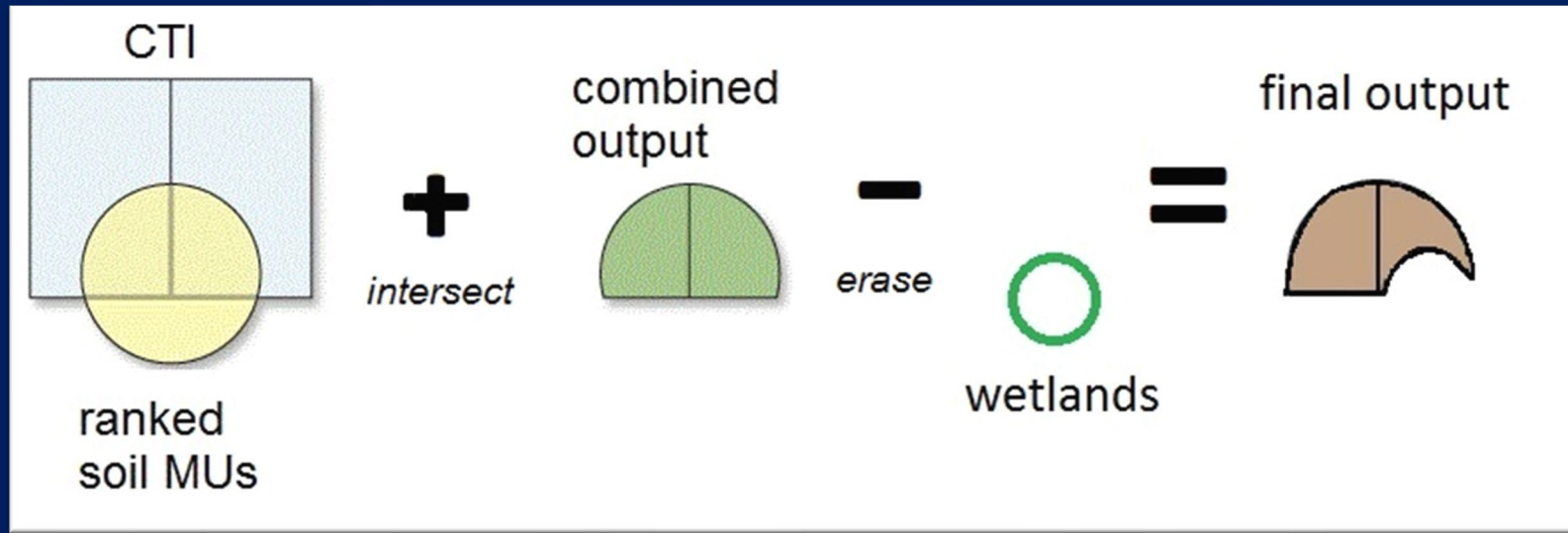
B = hydric soils (*polygons*)

W = current wetland boundaries
(*polygons*)

U = incompatible land uses (e.g., urban)

+ = Intersect ArcGIS tool

- = Erase ArcGIS tool



Developing a Machine Learning Approach

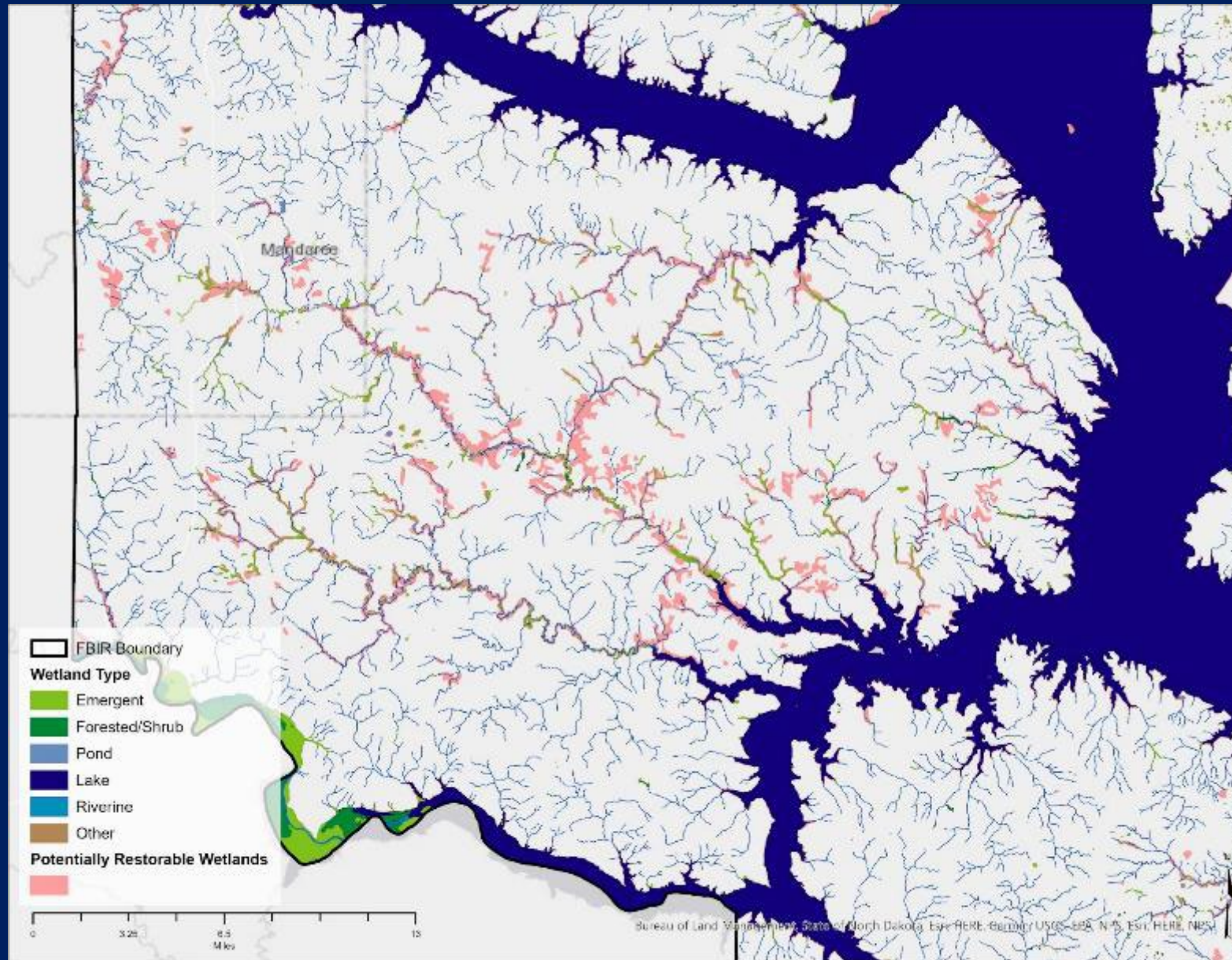
LiDAR Data Derivatives	Soil Data Derivatives	Vegetation/Land Cover
✓ Contour Topographic Index	✓ Hydric Soils	CropLand
Slope	Drainage Condition	Historic Vegetation
Aspect	Flooding Frequency	Land Cover/Land Use
Curvature	Soil Texture	Pre-settlement Vegetation
Drainage Ditches	Soil Porosity	✓ NWI
Flow Direction	Saturation	Local Wetland Inventory
Flow Accumulation		
Height Above Nearest Drainage		

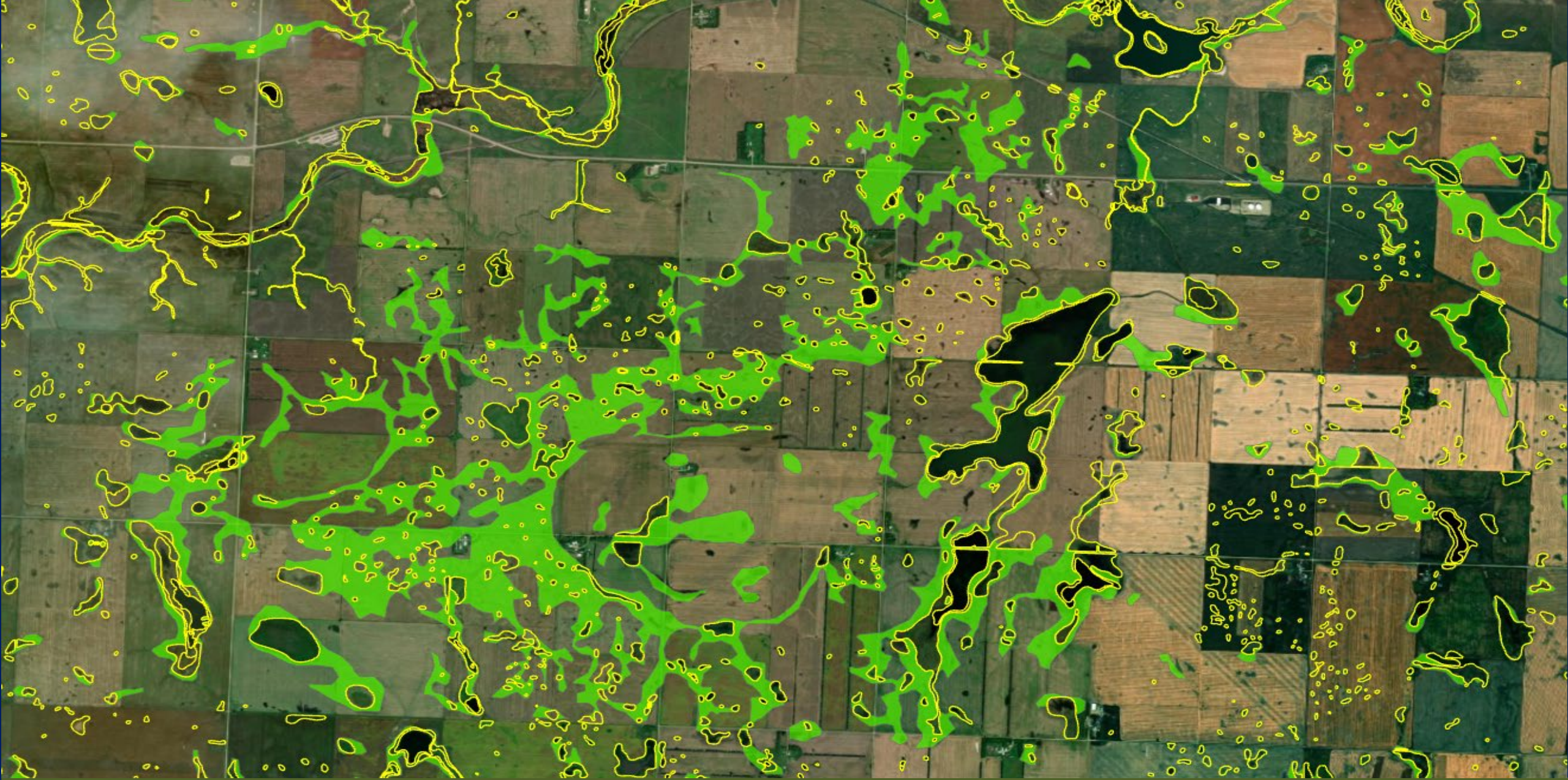
Optimized Random Forest

- **Variables**
- CTI
- Surface Curvature
- Hydric Soils
- Slope
- Soil Wetness
- Potential Wetland Landscape
- Water Regime
- **Confusion Matrix**

Accuracy	0.8240
Sensitivity	0.7046
Specificity	0.8849
Precision	0.7574
Recall	0.7046
F1 Score	0.7300



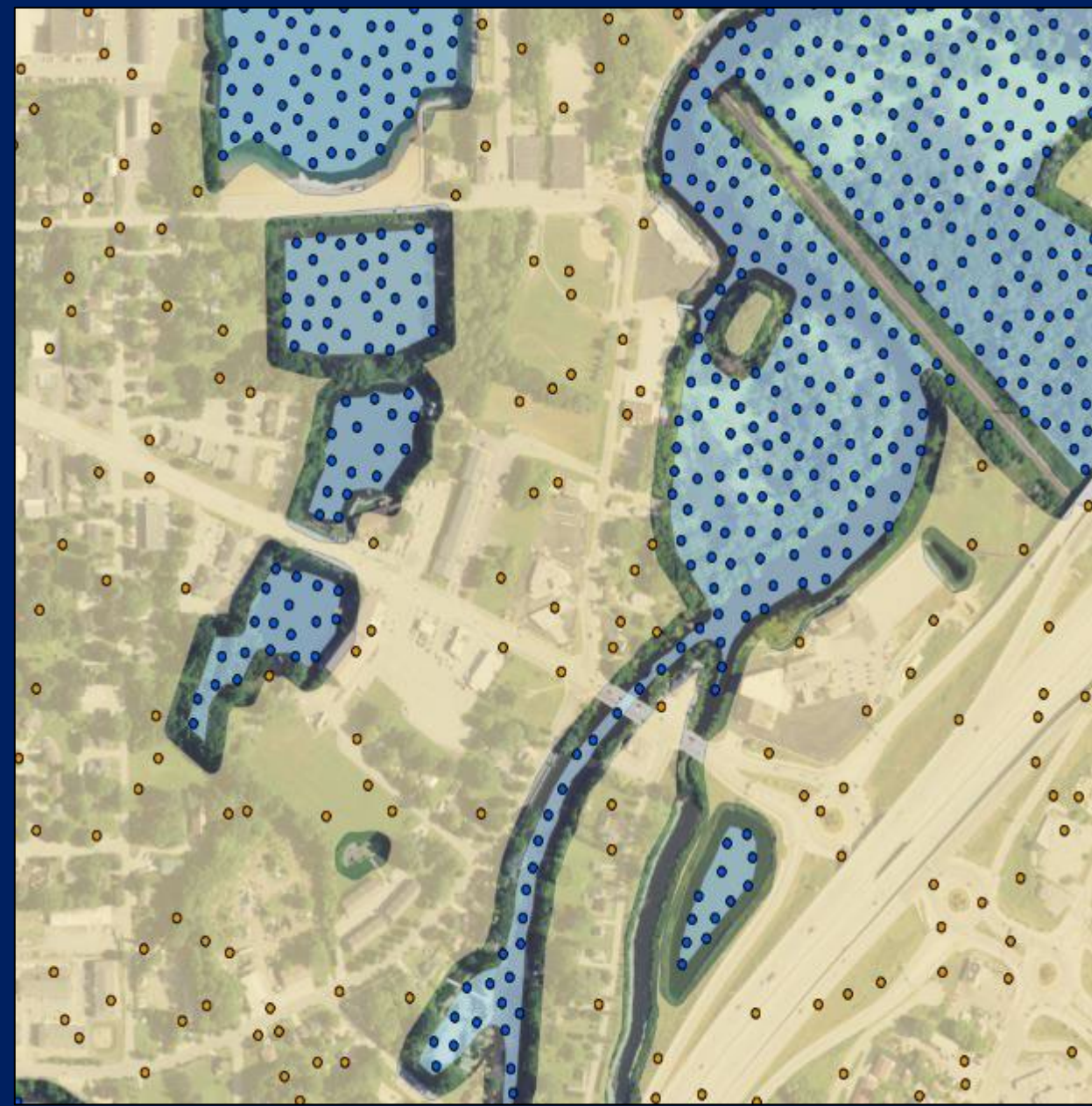




Optimized Random Forest Model

LiDAR DEM Derivatives	Hydric Soils	Reflectance (NAIP)	Hydrologic
Curvature *	SSURGO percent hydric *	NDVI *	NHD waterbodies and streams
Topographic Wetness Index* (TWI)	SSURGO water regime*	6 class landcover*	HUC 12 watershed boundaries
Depth to Water Index (DTW)*			Wetland training polygons

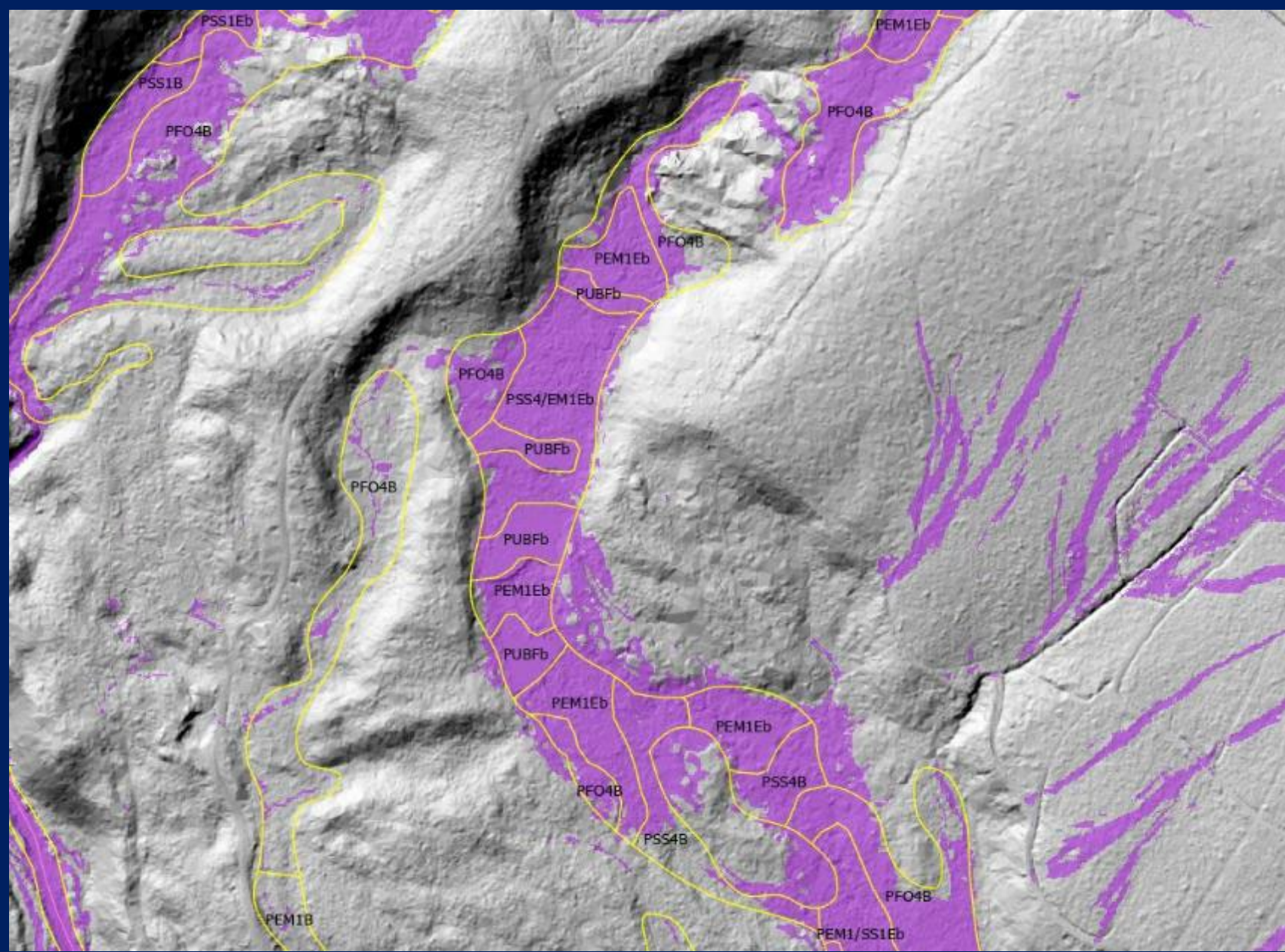
* Predictor variables used in RF classification



Beaver Created Wetlands



Beaver Created Wetlands



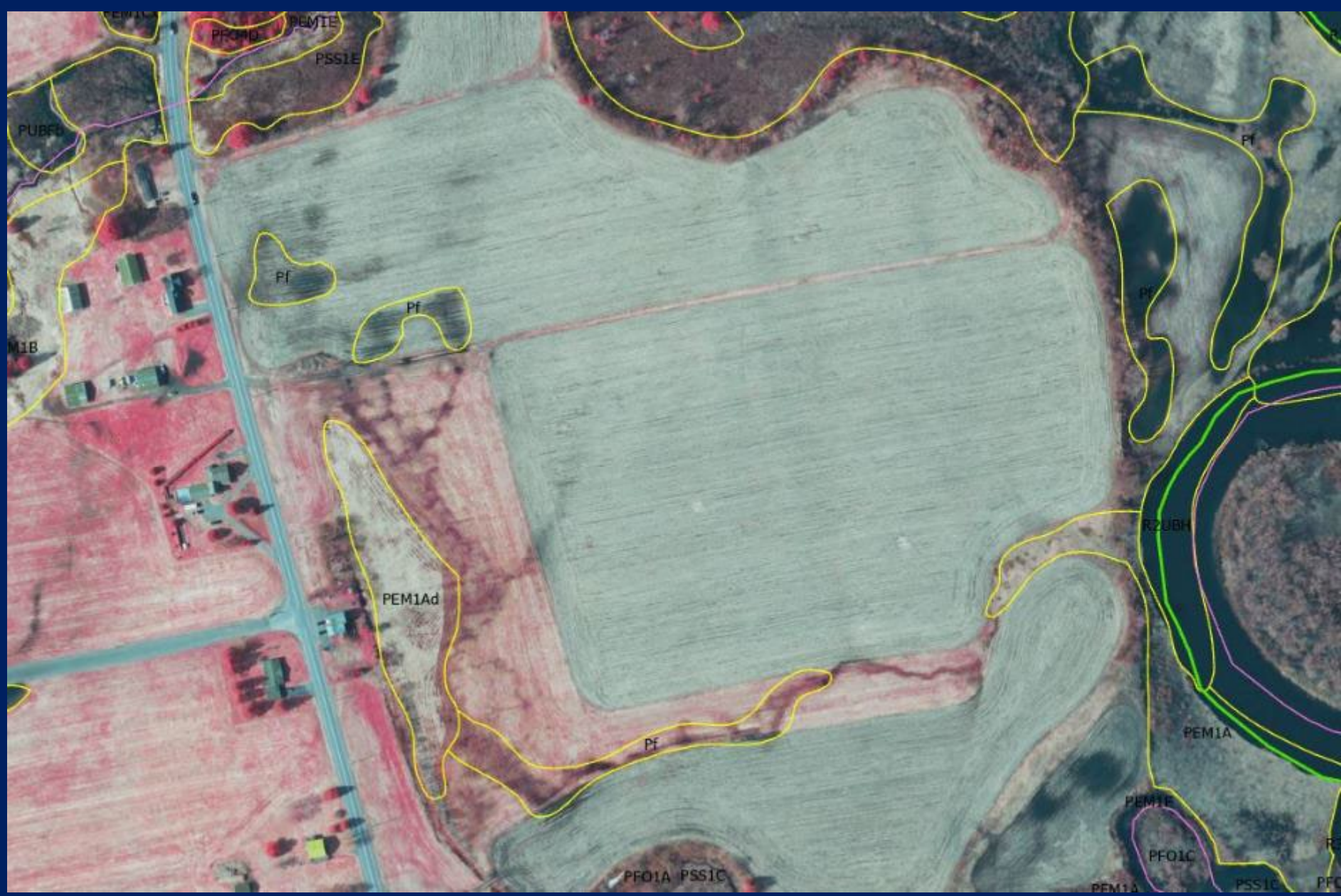
Beaver Created Wetlands



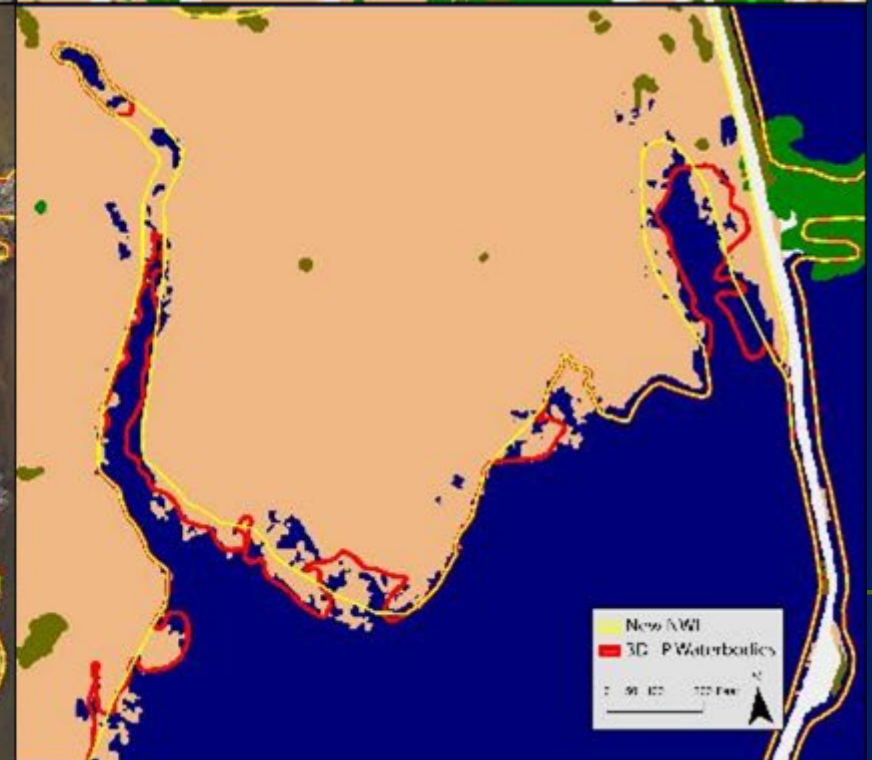
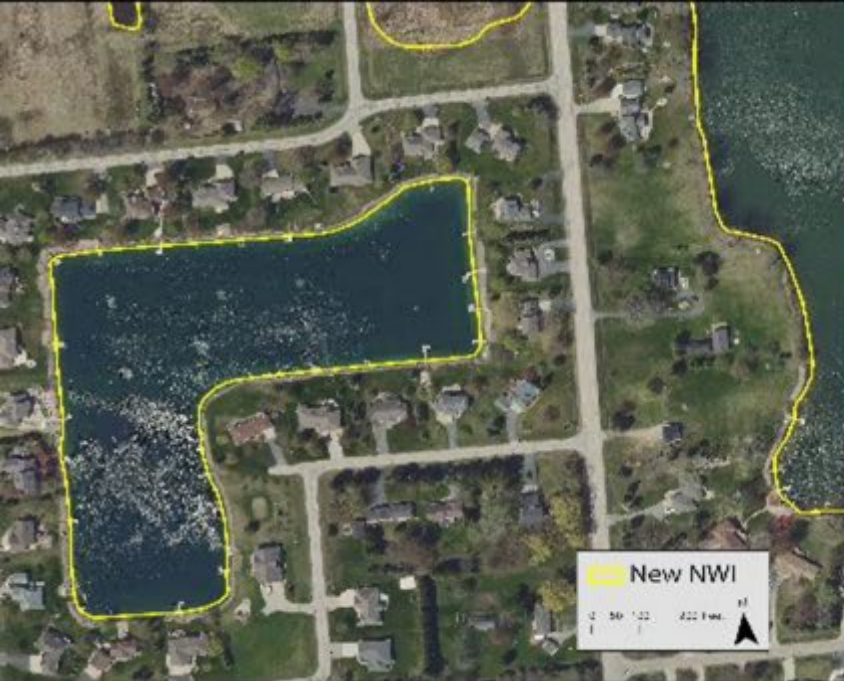
Farmed Wetlands



Farmed Wetlands







Lessons Learned

Three elements we know conflict are source data, vintage, and feature representation

– Source data

- 3DHP: Lidar: 3DEP Vintage 2015, 2018, 2020
- NWI: Imagery: Latest Vintage 2023
- CCAP: Imagery: NAIP Vintage 20/21

– Water bodies

- 3DHP: MMU 0.25 acres (vector – semi-automated)
- NWI: MMU 0.25 acres – vegetated;
0.1 acres – water (vector – manual)
- CCAP: MMU 0.25 acres (1 m pixels – semi-automated)

– Rivers

- 3DHP: Min width (15 m)
- NWI: Min width (15 ft)
- CCAP: (3 pixels of open water 3 m, not a rule)



Lessons Learned

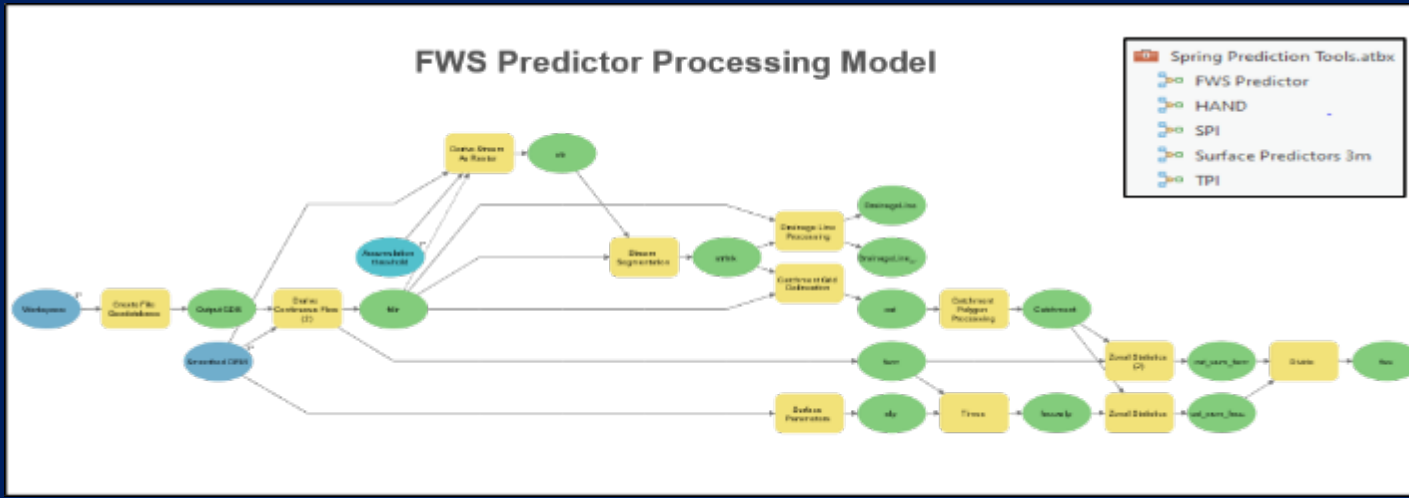
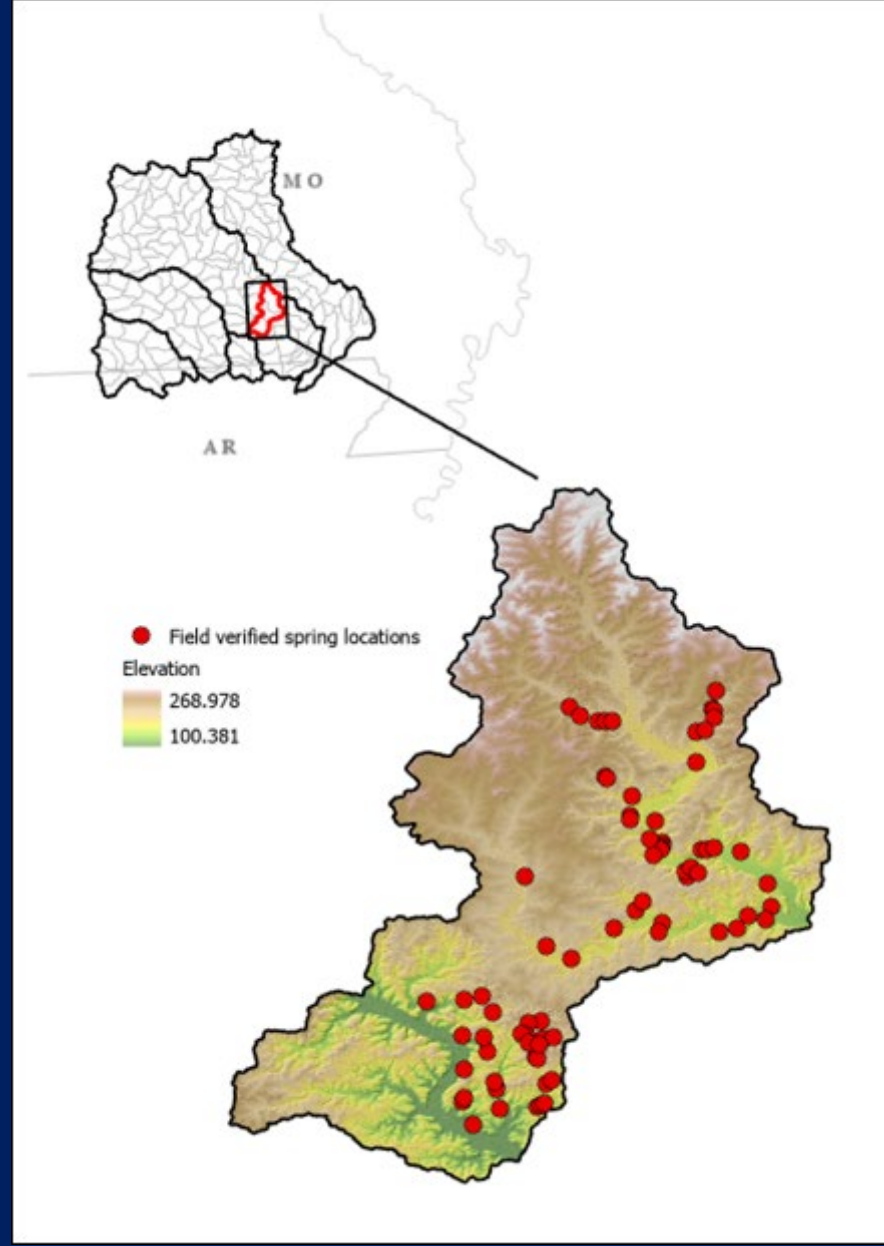
Logical Consistency Between Datasets

- Watersheds (WBD)
 - Process revised boundaries early
 - Eliminate time revisiting extents - NWI and CCAP
- EDH and NWI
 - Source data requirements
 - EDH lines contained within NWI polygons
 - Flowlines forming the edges of wetland features
 - Conduct full hydro-enforcement as an initial step
 - Cost savings of up to 20% in NWI data production
- NWI and C-CAP Consistency
 - Enforce vegetation breaks from NWI in C-CAP
 - Utilize NWI wetlands as C-CAP wetlands

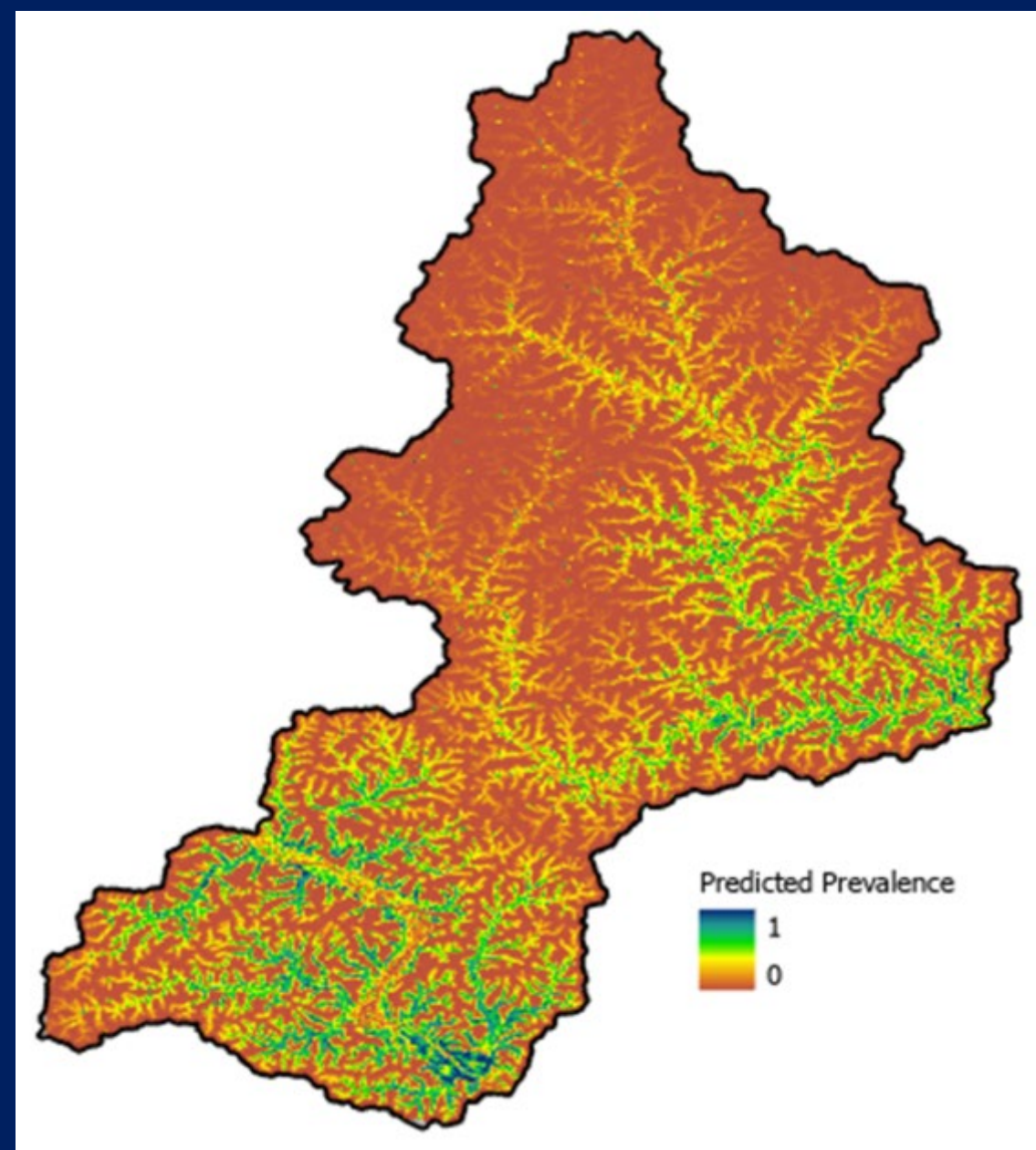
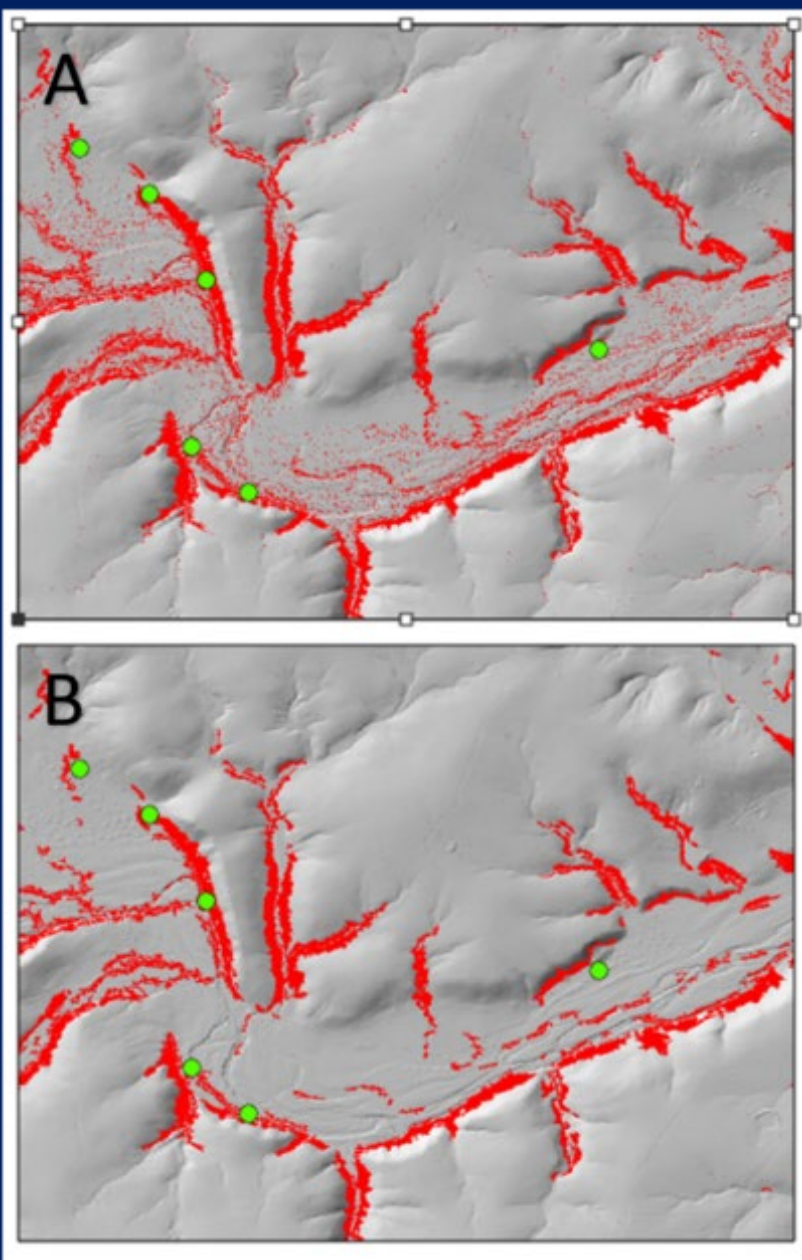


MaxEnt Machine Learning Algorithm GDE Landscapes

Predictor Variable	Description
fws	flow weighted slope
profcurv	profile curvature
plancurv	planform curvature
tancurv	tangential curvature
casocurv	Casorati curvature
torsion	contour geodesic torsion
tri	terrain ruggedness index
tpi	topographic position index
vrn	vector ruggedness measure
strdens	stream density
strdist	distance from stream
spi	stream power index
slp	slope
hand	height above nearest drainage
dem	elevation
twi	topographic wetness index



Results





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